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On future of robust control in smart grids

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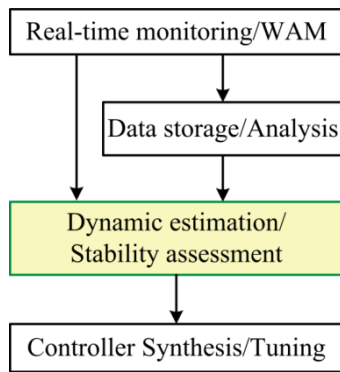


Fig. 2. Measurement-based control synthesis

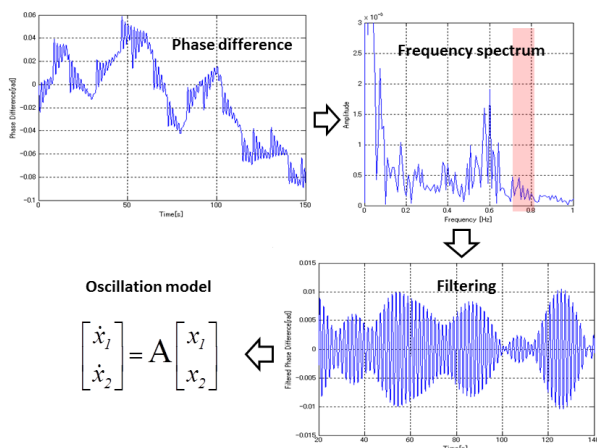


Fig. 3. Oscillation model estimation using phasor measurement

This method is descriptively shown in Fig. 3, and extensively explained in [1].

III. COMPLEXITY OF CONTROLLERS

In practice, many control systems usually track different control objectives such as stability, disturbance attenuation and reference tracking with considering practical constraints, simultaneously. In the power grid applications, it is usually desirable to meet all the specified goals using controllers with simple structures. Since, practically conventional controllers are commonly designed based on experiences, classical and trial-and-error approaches, they are incapable of obtaining desirable dynamical performance to capture all design objectives and specifications for a wide range of operating conditions and various disturbances.

It is significant to note that because of using simple structure, pertaining to a low-order control synthesis for dynamical systems in the presence of strong constraints and tight objectives are few and restrictive. Under such conditions, the control synthesis process may not approach to a strictly feasible solution. Therefore, most of robust control approaches suggest complex state-feedback or high-order dynamic controllers. Moreover in the most of proposed approaches, a single performance

criterion has been used to evaluate the robustness of resulted control systems.

This speech addresses some systematic, fast and flexible algorithms to design of low order robust controllers applicable in various control level/type of smart grids. The developed strategies attempt to invoke the strict conditions and bridge the gap between the power of robust control theorems and reality of smart grid controls.

Fig. 4 shows the main steps of the developed algorithms. In the proposed methodology, after selection of a proper robust control theorem to find an optimal performance index (γ), the given control design is reduced to a more simple control synthesis (e.g. static output feedback control). Then the optimal controller gains are found out using an iterative linear matrix inequalities (ILMI) algorithm such that the specified optimal performance index to be closely tracked. To illustrate the effectiveness of the proposed control strategies, several examples with detailed explanations are given in [2].

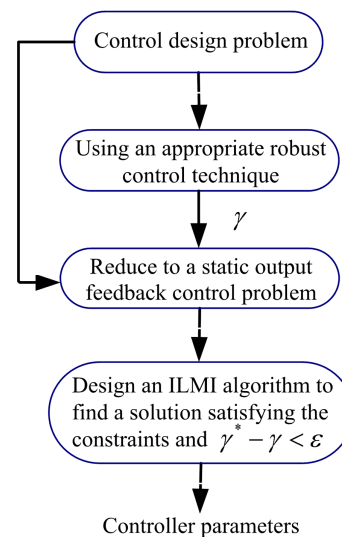


Fig. 4. A synthesis framework for designing robust controllers with simple structures.

IV. CONCLUSION

In this speech, the capability of robust control to solve various power system control problems is emphasized. The most important challenges in front of application of well-known robust control techniques in modern power grids (smart grids) are discussed. Finally, to illustrate the presented issues, several synthesis examples are reviewed.

REFERENCES

- [1] H. Bevrani, M. Watanabe, Y. Mitani, *Power system monitoring and control*, Wiley-IEEE, NY, 1 Ed., May 2014.
- [2] H. Bevrani, *Robust power system frequency control*, Springer, NY, 2 Ed., July 2014.