



Linear Control Systems

Course Description

Hassan Bevrani

Professor, University of Kurdistan

Spring 2024

Contents

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Instructor

Hassan Bevrani
حسن بیورانی

Academic Activities Locations

Iran: Bachelor and Master, Lecturer, Professor (1995-2019)

Japan: PhD, Postdoc, Visiting Professor (2002-2023)

Australia: Senior research fellow, Senior Lecturer (2007-2008)

France: Visiting Professor (2014-2016)

Germany: Visiting Professor (2017-2018)

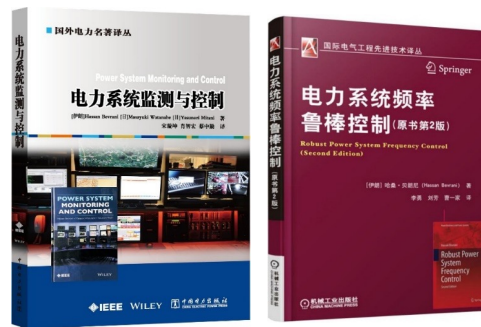
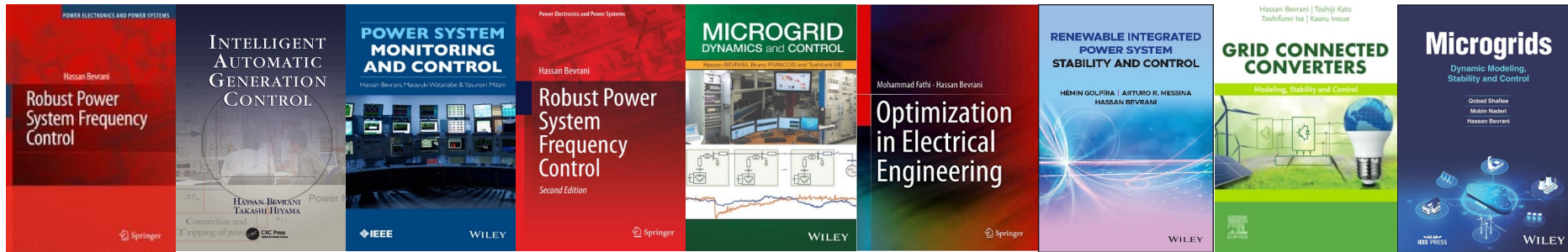


Publications

450 Papers

15 Book Chapters

9 Books



Google Scholar Citations

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Hassan Bevrani

FOLLOWING

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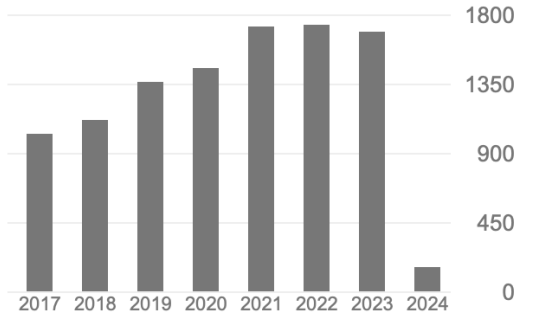
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	H Bevrani, T Ise, Y Miura International Journal of Electrical Power & Energy Systems 54, 244-254			
<input type="checkbox"/>	Renewable energy sources and frequency regulation: survey and new perspectives		649	2010
	H Bevrani, A Ghosh, G Ledwich IET Renewable Power Generation 4 (5), 438-457			



Home Page

<https://research.uok.ac.ir/~bevrani>

September 24, 2020

 University of Kurdistan

فارسی



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Faculty: Faculty of Engineering

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- Webinar: Smart Grids for Smart Cities
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Course Description

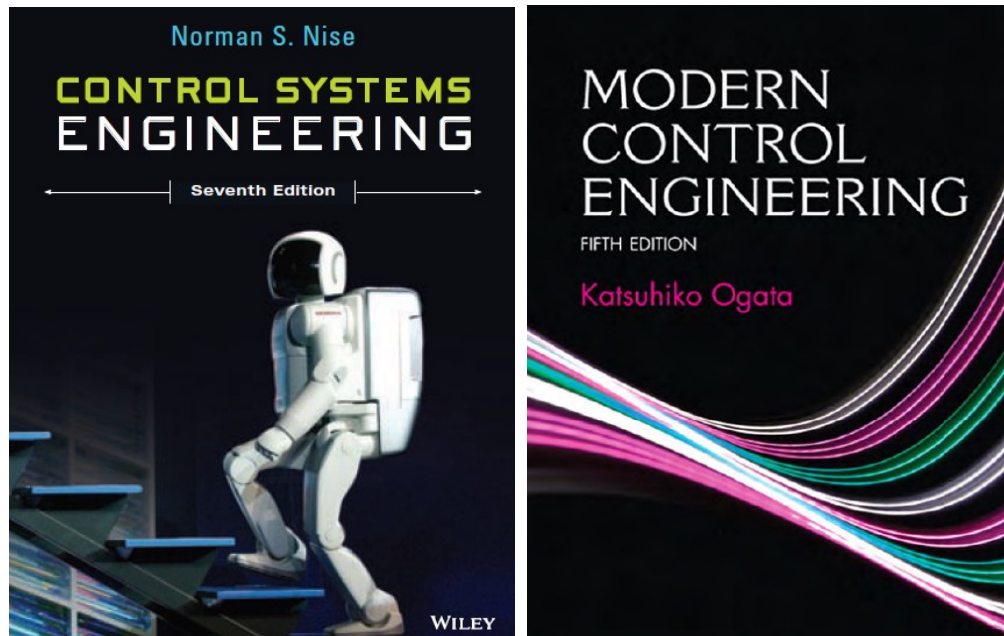
This course addresses the linear control theory and techniques for **analysis** and **synthesis** of **control systems**. The course material will include some fundamental concepts on dynamic system **modeling** and control design. Basic methods and tools for **stability** and **performance** analysis of linear dynamic systems will be introduced.

Course Outline

1	An Introduction on Control Systems
2	Laplace Transformation and Mathematical Models
3	Control Systems Characteristics
4	Stability of Linear Feedback Systems
5	The Root Locus Method
6	Frequency Response Methods
7	State-Space Analysis
8	Design of Feedback Controllers

References

- [1] H. Bevrani, **Course Lecture Notes**, Spring Semester, 2024.
- [2] K. Ogata, **Modern Control Engineering**, 5th Ed., Prentice Hall, 2010.
- [3] Norman S. Nise, **Control Systems Engineering**, 7th Ed., Wiley, 2015.



Course Objectives

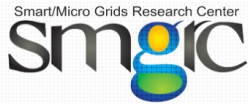
1. A deep knowledge on the preliminary concepts, frameworks, and components of a Linear Control system,
2. Learning how to find a simple mathematical model for an electrical/mechanical system,
3. Understanding different definitions for stability and performance characteristics,
4. Learning how to analyze a control system using several time and frequency response methods,
5. Design a basic controller for a given system by programming and simulation in MATLAB environment.

Course Grading

Item	(%)	Comment
Attending and Activities	10	Shows your interest/respect
Homework	20	8-12 assignments
Mid-Term Exam 1	20	After Chapter 3
Mid-Term Exam 2	20	After Chapter 6
Final Exam	30	TIR 3 rd , 1403

Course Webpage

<https://smgrc.uok.ac.ir>



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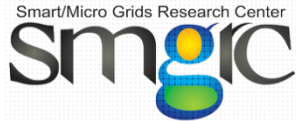
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- Linear Control-University of Kurdistan 2024

Linear Control-Spring 2024 University of Kurdistan

Here, enrolled students can access relevant course materials via the provided links.
Explore and enhance your learning experience with the resources available.

Course ID: 7012038-01

Course Name: Linear Control

Academic Year: Spring 2024

Lecturer(s): [Dr. Hassan Bevrani](#)

PDF of the Lectures:

Num.	Lecture Name	Download Section
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00	L0-Course Description	Click Here
01		Click Here

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Contact e-mail for this Course

- **Please only submit your homework and project reports to the following email address:**

bevranih18@gmail.com

- Please use the following term as subject of your email:

Family Name_RAW_HW3 (for HWs)

Family Name_RAW_Project (for Project)

- For writing a formal email you can use the following link:

<https://www.aparat.com/v/8iXW9>

Teaching Assistant (TA)

- **The TA for this course will be introduced in the class.**

Thank You!

